

Challenges in Atmospheric Correction and Vicarious Calibration

Constant Mazeran, solvø, France



amt4sentinelrm

workshop, Plymouth, 20.06.2017

Content

- Calibration and validation of Ocean Colour Radiometry - **OCR**
- Consistency of the overall process comprising
 - Vicarious calibration - **VCAL**
 - Validation - **VAL**
 - Mission operation – **OP**
- Standard atmospheric correction: Gordon & Wang, Antoine & Morel

Integrated view on VCAL/VAL/OP

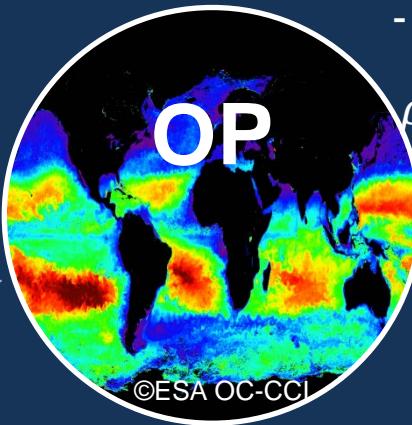
- One or a few optimal site(s)

- FRM of ρ_w^t

$$g(\lambda) = \frac{t(\lambda)\rho_w^t(\lambda) + \rho_{path}(\lambda)}{\rho_{gc}(\lambda)}$$
$$= 1 - \frac{\Delta\rho_w}{\rho_w^t} \cdot \frac{t\rho_w^t}{\rho_{gc}}(\lambda)$$



Consistency ?



- Global maps of OCR & uncertainty

$$\rho_w(\lambda) = \frac{\bar{g}(\lambda) \cdot \rho_{gc}(\lambda) - \rho_{path}(\lambda)}{t(\lambda)}$$

- Dataset of points over the ocean

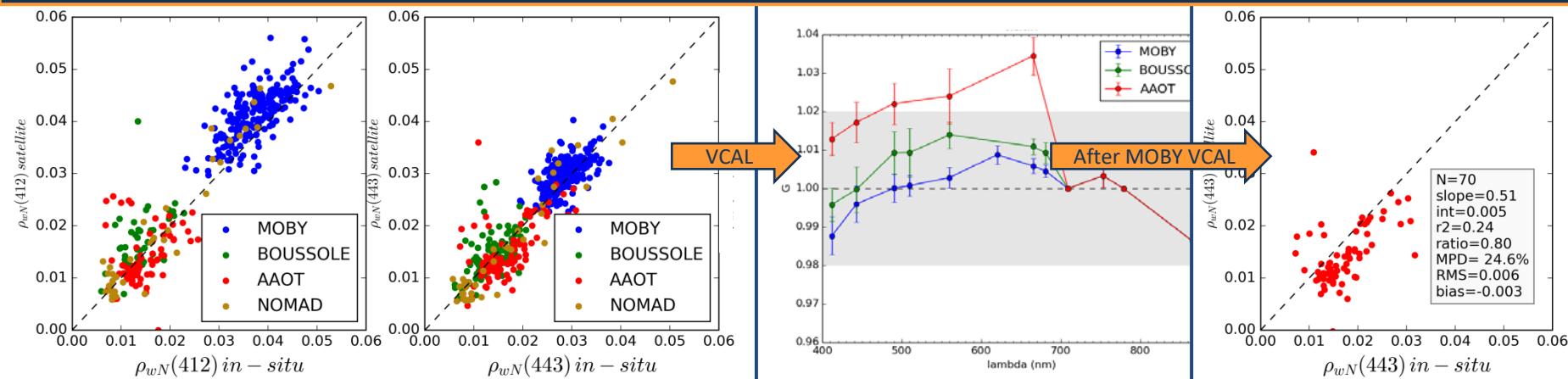
- FRM of ρ_w^t and possibly AOT

$$\Delta\rho_w(\lambda) = \frac{\rho_w(\lambda) - \rho_w^t(\lambda)}{\rho_w^t(\lambda)}$$

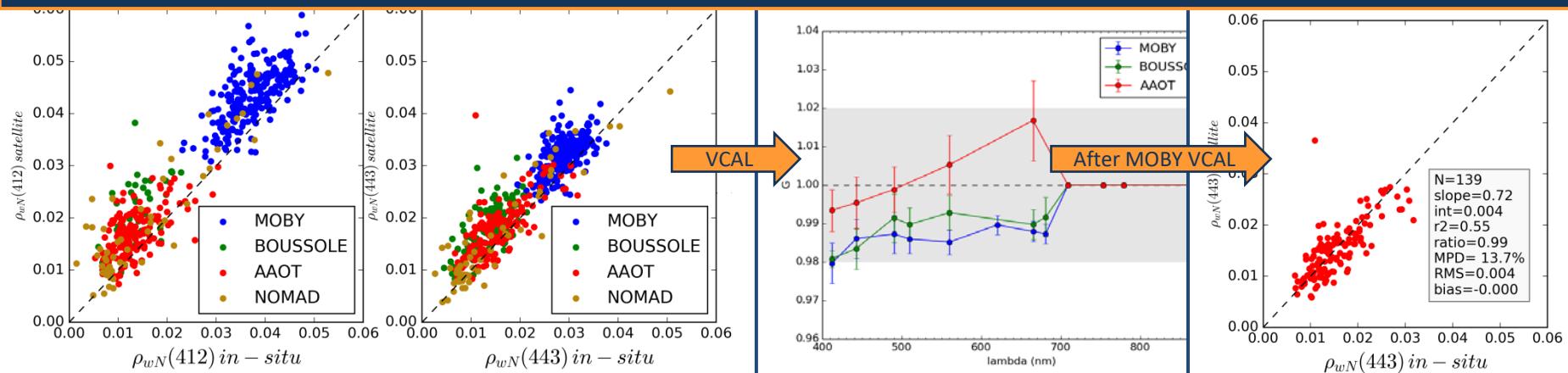


Example: MERIS 3rd reprocessing

MERIS 3RP



MERIS 3RP + improved Bright Pixel Atmospheric Correction (BPAC)



Error and uncertainty in OCR

- For **VAL**, in terms of relative error on ρ_w :

$$\frac{\Delta \rho_w}{\rho_w^t} = \left(\frac{\Delta \rho_{gc}}{\rho_{gc}} \cdot \frac{\rho_{gc}}{t \rho_w^t} - \frac{\Delta \rho_{path}}{\rho_{path}^t} \cdot \frac{\rho_{path}^t}{t \rho_w^t} - \frac{\Delta t}{t^t} \right) / \left(1 + \frac{\Delta t}{t^t} \right)$$

calibration *AC*

- For **OP**, in terms of relative uncertainty on ρ_w (cf. GUM):

$$\begin{aligned} \left(\frac{u(\rho_w)}{\rho_w} \right)^2 \approx & \left(\frac{u(\rho_{gc})}{\rho_{gc}} \right)^2 \cdot \left(\frac{\rho_{gc}}{t \rho_w} \right)^2 + \left(\frac{u(\rho_{path})}{\rho_{path}} \right)^2 \cdot \left(\frac{\rho_{path}}{t \rho_w} \right)^2 + \left(\frac{u(t)}{t} \right)^2 \\ & + 2 \frac{u(\rho_{path}, t)}{t \rho_{path}} \cdot \left(\frac{\rho_{path}}{t \rho_w} \right)^2 \end{aligned}$$

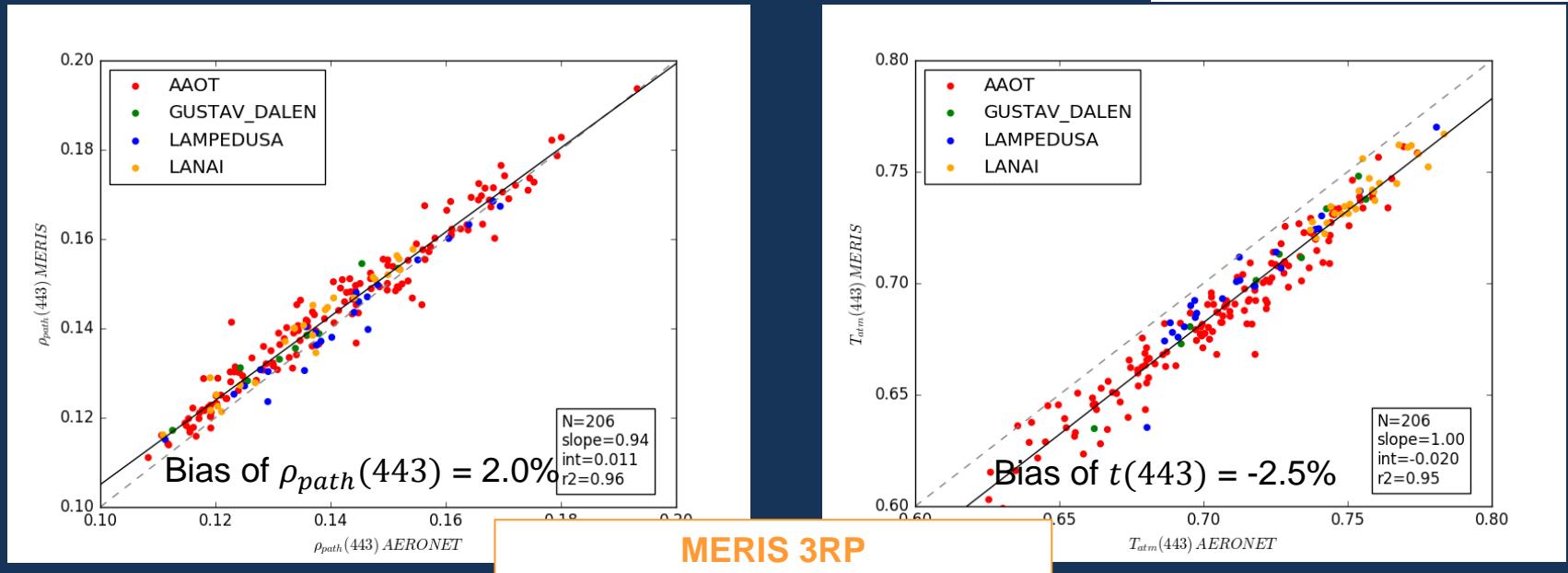
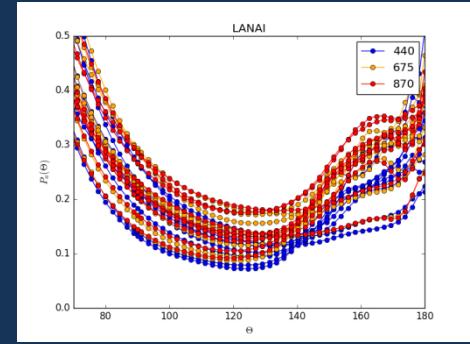
- For **VCAL**, in terms of uncertainty on gains:

$$u(g) \approx \frac{t \rho_w^t}{\rho_{gc}} \sqrt{\left(\frac{u(\rho_w^t)}{\rho_w^t} \right)^2 + \left(\cancel{\frac{u(\rho_{path})}{\rho_{path}}} \right)^2 \cdot \left(\frac{\rho_{path}}{t \rho_w^t} \right)^2 + \cancel{\left(\frac{u(t)}{t} \right)^2} + 2 \cancel{\frac{u(\rho_{path}, t)}{t \rho_{path}}} \cdot \left(\frac{\rho_{path}}{t \rho_w^t} \right)^2}$$

by principle of System Vicarious Calibration

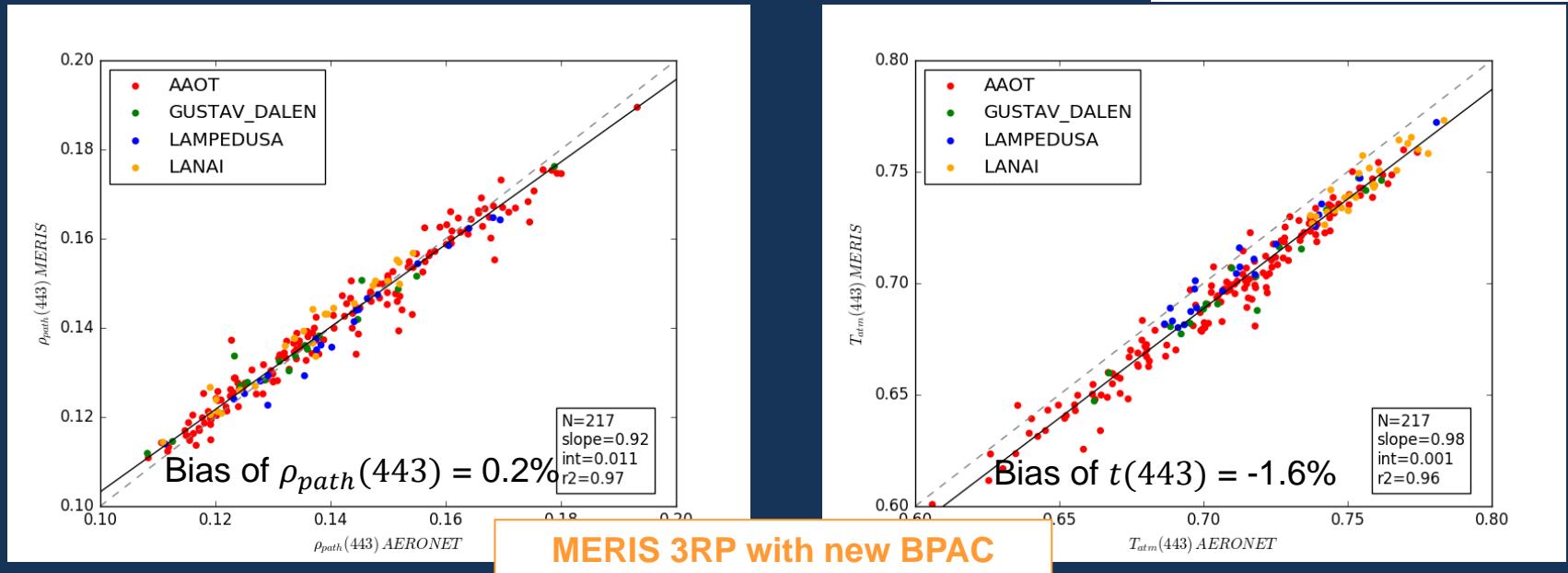
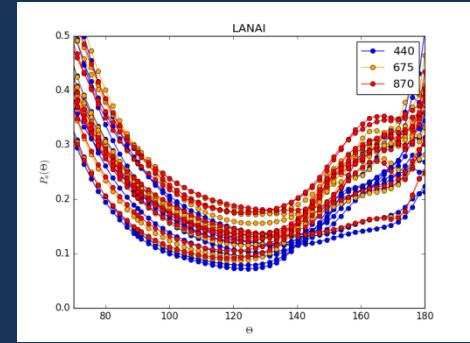
Error in atm. scattering functions

- **AERONET aerosol IOPs** (phase function, single scattering albedo, extinction coefficient) from inversion of solar extinction and sky radiance – Limited in bands.
- **Radiative transfer model** applied to MERIS acquisition matching AERONET: temporal interpolation or $\Delta t < 3\text{h}$, no glint, no cloud or ice haze, no PCD flags $\rightarrow \rho_{path}^t$ and t^t



Error in atm. scattering functions

- **AERONET aerosol IOPs** (phase function, single scattering albedo, extinction coefficient) from inversion of solar extinction and sky radiance – Limited in bands.
- **Radiative transfer model** applied to MERIS acquisition matching AERONET: temporal interpolation or $\Delta t < 3\text{h}$, no glint, no cloud or ice haze, no PCD flags $\rightarrow \rho_{path}^t$ and t^t



Consistency in atm. & marine error?

- Can we achieve consistency between uncertainty provided by ρ_{path}^t , t^t (AERONET) and uncertainty provided by in situ ρ_w^t ?

$$\frac{\Delta \rho_w}{\rho_w^t} = \left(\frac{\Delta \rho_{gc}}{\rho_{gc}} \cdot \frac{\rho_{gc}}{t \rho_w^t} - \frac{\Delta \rho_{path}}{\rho_{path}^t} \cdot \frac{\rho_{path}^t}{t \rho_w^t} - \frac{\Delta t}{t^t} \right) / \left(1 + \frac{\Delta t}{t^t} \right)$$

In situ ρ_w^t $= 1 - g$ AERONET

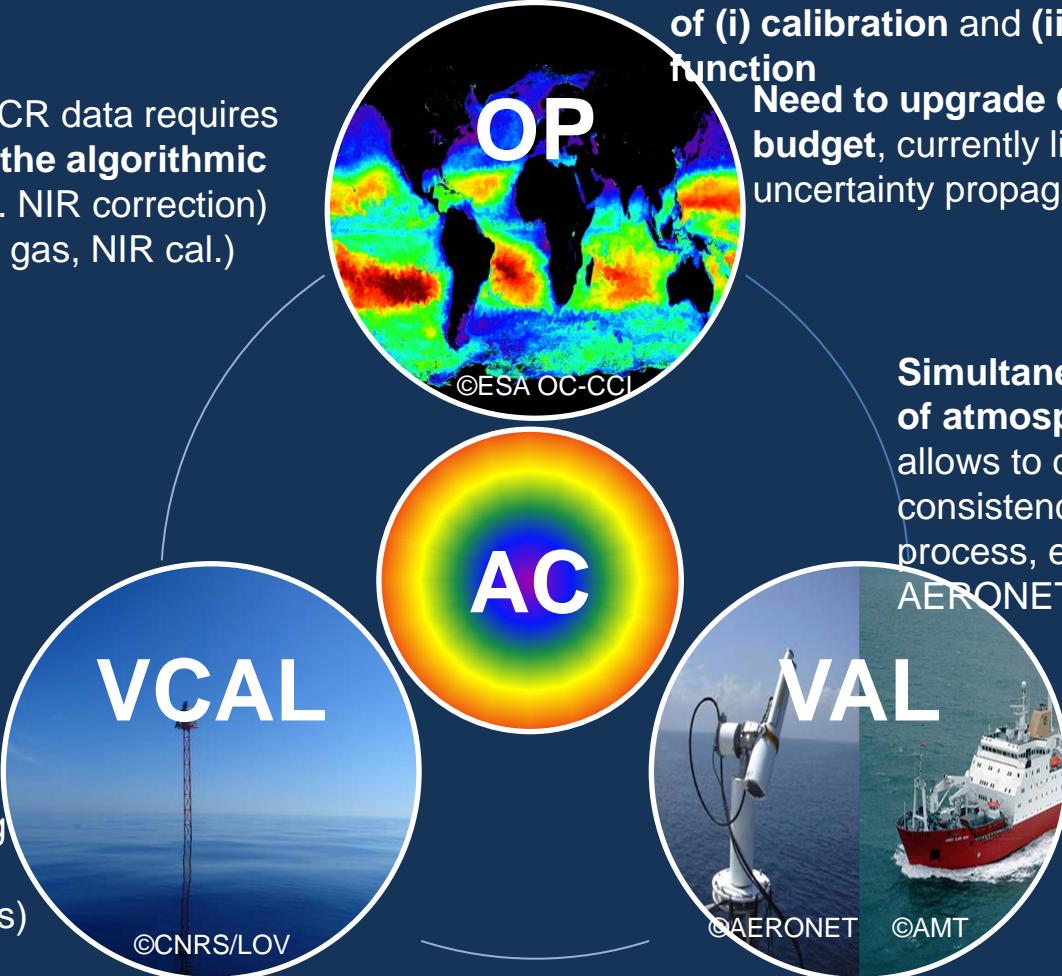
LANAI – $\lambda = 443$ nm		
	MOBY	AERONET and $g=0.975$
Mean rel. diff.	1%	2%
Mean abs. rel. diff.	7%	9%
RMS	$3.1 \cdot 10^{-3}$	$3.5 \cdot 10^{-3}$

AAOT – $\lambda = 443$ nm		
	AERONET-OC	AERONET and $g=0.996$
Mean rel. diff.	-13%	-12%
Mean abs. rel. diff.	16%	22%
RMS	$4.8 \cdot 10^{-3}$	$6.1 \cdot 10^{-3}$

MERIS 3RP

Conclusion

Producing consistent OCR data requires an **integrated view on the algorithmic chain**: VCAL + AC (incl. NIR correction) + upstream steps (glint, gas, NIR cal.)



Uncertainty of OCR is related to **uncertainty of (i) calibration and (ii) atm. scattering function**

Need to upgrade OLCI uncertainty budget, currently limited to radiometric uncertainty propagation (noise)

Simultaneous measurements of atmospheric IOP + OCR allows to demonstrate the consistency of the overall process, e.g. AERONET + AERONET-OC

Thank you

Acknowledgment:

- **Francis Zagolski, solvō**: Radiative transfer model
- **Gerald Moore, Bio-Optika & Jean-Paul Huot, ESA**: BPAC
- **Ken Voss, University of Miami**: MOBY data
- **David Antoine, LOV**: BOUSSOLE data
- **Giuseppe Zibordi, JRC**: AERONET & AERONET-OC data
- **Brent Holben, NASA & Daniela Meloni, ENEA**: AERONET data
- **Jeremy Werdell & Sean Bailey, NASA**: NOMAD database
- **ACRI, ARGANS & ESA**: MERMAID database & ODESA processor
- **Brockmann Consult**: Calvalus data extraction

Funding: ESA IDEAS+ SPPA (Phase 2) & EC/JRC



SPPA

Sensor Performance, Products and Algorithms



Consistency in MERIS 4th reproc.

- Various improvements achieved by MERIS QWG (L1b, classif, BPAC, AC ...)
- MOBY and BOUSSOLE gains agreement: Chi2 test of homogeneity: if $\frac{|\bar{g}_M - \bar{g}_B|}{\sqrt{\sigma_M^2/N_M + \sigma_B^2/N_B}} < 1.96$, there is 95% probability that both sets of gains belong to the same distribution

